

NEURO SWING 2 into NEURO HiSWING

This online tutorial describes the conversion of a system ankle joint with plug + go modularity to a NEURO HiSWING system ankle joint with plug + go modularity using the NEURO SWING 2 system ankle joint as an example. Due to their construction, all system ankle joints with plug + go modularity can be converted among each other by exchanging the functional unit. Further information on this can be found in the online tutorial on the assembly of system ankle joints with plug + go modularity.

You can find more information about the system ankle joints in the [instructions for use](#) for system ankle joints with plug + go modularity and in the [instructions for use](#) for the NEURO HiSWING.

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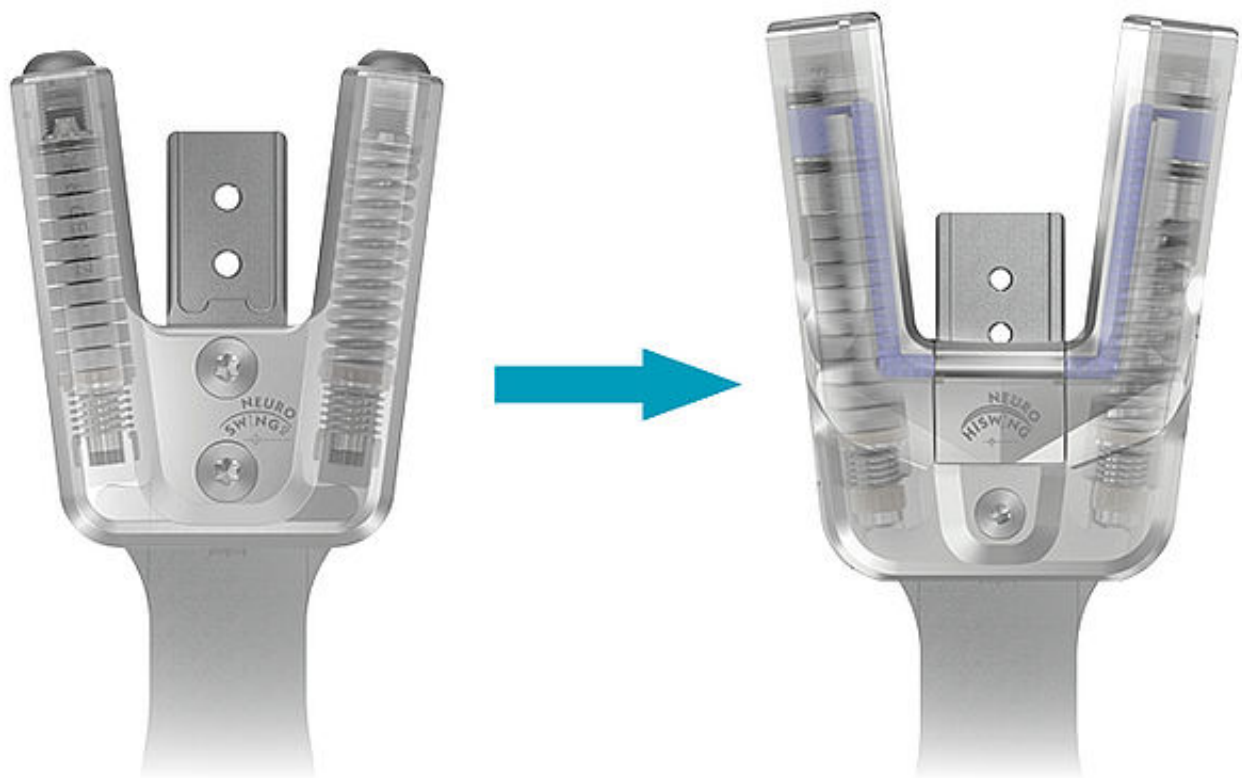
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You can convert the NEURO SWING 2 as well as all system ankle joints plug + go modularity to a NEURO HiSWING system ankle joint in just a few steps. The NEURO HiSWING system ankle joint offers individual adjustment options for the ankle joint angle.

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To convert the system ankle joint to a NEURO HiSWING so, you need:

- the NEURO HiSWING functional unit with the corresponding system width,
- a spirit level,
- a T6 hexalobular screwdriver/bit.

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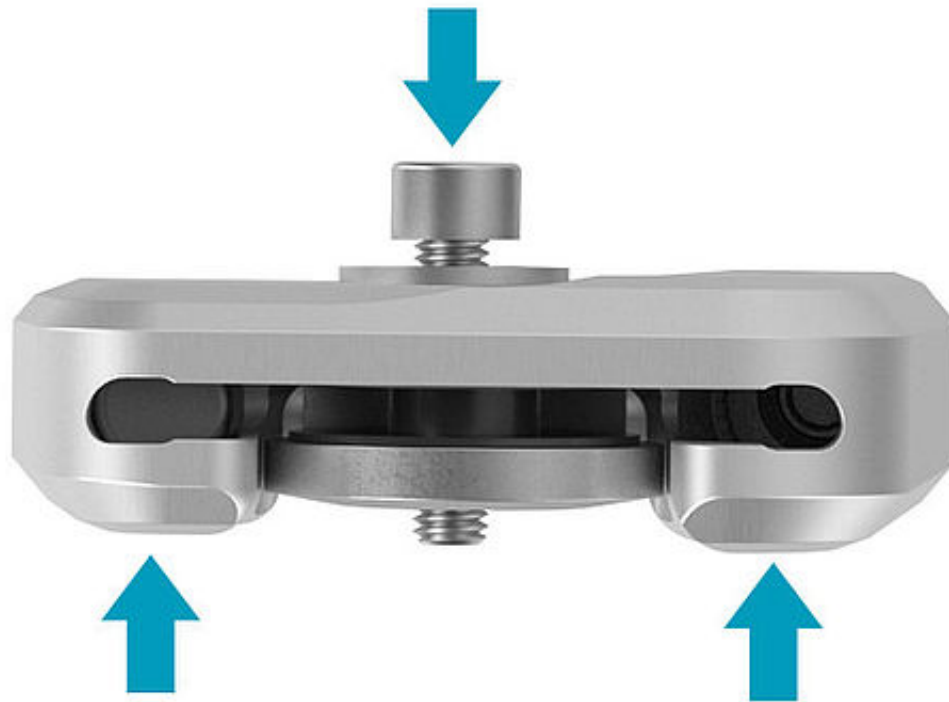
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To demount the functional unit, proceed as follows:

- Unscrew both countersunk flat head screws.
- Place the washer on the functional unit and screw the pressing screw into the thread of the first screw. The pressing screw must not be screwed in completely.
- Push the joint's upper part and the functional unit apart by exerting force on them as illustrated (see arrows). This can be achieved by using a vice or by controlled knocks.
- Remove pressing screw and washer again.



Clean the areas to be adhered. Mix a small amount of AGOMET® F330. Adhere the spirit level onto the prepared area. Mind the safety data sheet and let the adhesive cure sufficiently.

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For the joint assembly of the NEURO HiSWING, follow the steps in the online tutorial "[Joint Assembly of System Ankle Joints with plug + go Modularity](#)".

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