## FIOR \& GENTZ Tools



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## e-Cast



| h-Cast |  |  |
| :---: | :--- | :--- |
| Fig. | Article Number |  |
| 1 | WE3200 | h-Cast |
| 1a | WE3200-1/5 | cover plate |
| 1b | WE3200-1/4 | plate with tenon, 5 mm |
| 1c | WE3200-1/3 | plate with tenon, 10 mm |
| 1d | WE3200-1/2 | plate with tenon, 20 mm |
| 1e | WE3200-1/1 | base plate with tenon |

Application: to determine a heel height/leg length discrepancy.
For positioning the patient in a physiological position.

| e-Cast in a Case |  |  |
| :---: | :---: | :---: |
| Fig. | Article Number | Description |
| 2 | WE3400 | e-Cast in a case |
| 2a | ET3400-T | operator device |
| 2 b | ET3410-WE | sensor for the thigh |
| 2 c | ET3420-WE | sensor for the lower leg |
| 2d | ET3430-WE | sensor for the foot |
| 2 e | WZ2067-T08 | screwdriver, hexalobular socket, $\mathrm{T} 8 \times 60 \mathrm{~mm}$ |
| $2 f$ | ET0710 | cable |
| 2 g | ET0780 | adapter |
| 2 h | ET0830-2450* | $3 \times$ batteries for e-Cast sensors* |
| w/o fig. | KL4200 | glue dots for the fixation of the sensors, 48 pieces |
| w/o fig. | KL4601 | washers for marking the mechanical pivot points, self-adhesive, 28 pieces |



* When reordering the article, only one battery is delivered as a sales unit.

Application: for checking the joint angles during the making of the negative cast

| e-Cast Accessory Parts |  |  |
| :---: | :---: | :--- |
| Fig. | Article Number | Description |
| $2 b, 2 c$ and $2 d$ | ET3400-WE | e-Cast sensor set for making the negative cast |



Knee joint: the position of the mechanical pivot point at knee height is calculated by the Orthosis Configurator using the ap measurement.

With the Orthosis Configurator, the exact anatomical compromise pivot point according to Nietert P1 and the exact mechanical pivot point P can be calculated for your planned orthosis. We recommend placing the orthotic knee joint exactly on the calculated mechanical pivot point $P$. To do so, mark point $P$ on the patient's leg according to our production technique. Later, the alignment aid (see catalogue page J 4 ) is pierced through this point $P$ on the negative cast.

## Why Does the Mechanical Pivot Point P Differ from the Anatomical Compromise Pivot Point According to Nietert P1?

Due to the rolling and sliding motion of the human knee, the anatomical pivot point moves on a centrode during flexion and extension. The anatomical compromise pivot point P1 centres the individual pivot points of the centrode as precisely as possible on only one point. For patients without any impairment on the muscles, it makes sense to place the axis of the orthotic knee joint on the anatomical compromise pivot point according to Nietert. To increase the mechanical knee control for patients with insufficient knee- and hip-securing muscles, the pivot point of the orthotic knee joint has to lie behind the anatomical compromise pivot point. How far the mechanical pivot point lies behind the anatomical compromise pivot point depends on the degree of insufficiency of the affected muscle groups. In order to reduce the bottom-up shifting of the femoral shell on the patient's leg and due to the difference to the centrode, the mechanical pivot point also has to lie further down.


P1 = anatomical compromise pivot point $P=$ mechanical pivot point

When the pivot point is optimally positioned, the course of the system side bars is approximately $50 \%$ due to the integrated posterior offset of the system knee joints. Please use our Orthosis Configurator:


Ankle joint: correct positioning of the mechanical pivot point at ankle height according to the study of Isman/Inman*


The mechanical axis is positioned in the frontal plane at the same level as the distal end of the fibula. The mechanical axis at ankle height is aligned to the centre of the lower leg and is parallel to the ground and perpendicular to the direction of movement under consideration of the individual external rotation.

- mechanical pivot point
* Isman RE, Inman VT (1969): Anthropometric Studies of the Human Foot and Ankle. Biomechanics Laboratory University of California.

anatomical axis at ankle height in the frontal plane (Isman and Inman, 1969)
In the recommended position, the mechanical axis intersects all of the functional axes (anatomical axis at ankle height and tibial longitudinal axis). Unintentional shifting of the orthosis and additional load on the ligamentous apparatus are kept to a minimum through the compromise axis. Depending on the footwear, it may be necessary to position the pivot point higher. This can lead to an impaired function of the mechanical joint due to the resulting movement of the orthosis.


## Alignment Aid (Fig. 1-2)

| Fig. | Article Number | Description | Unit |
| :---: | :---: | :---: | :---: |
| 1 | JA1001 | alignment aid $11 \times 11 \times 300 \mathrm{~mm}$ for 10 and 12 mm system ankle joints | piece |
| 2 | JA1000 | alignment aid $15 \times 15 \times 300 \mathrm{~mm}$ for all $14,16,20$ and 24 mm system joints as well as 12 mm system knee joints | piece |

Application: the alignment aid is pierced through the mechanical pivot points marked on the negative cast and serves as a placeholder for the holder (see catalogue page K5ff.).

| Calliper (Fig. 3) |
| :--- |
| Fig. |
| Article Number |
| WZ3000-32 |

Application: to determine the ap measurement at knee height

| Outside Calliper (Fig. 4) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Fig. | Article Number |  | Description | Unit |
| 4 | WZ3001-02 | outside calliper |  | piece |

Application: to determine the shoe sole thickness

piece
piece


| Holders and Joint Retainers |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| System Ankle Joints | Tools | Article Numbers for System Width |  |  |  |  |  |
|  |  | 10 mm | 12 mm | 14 mm | 16 mm | 20 mm | 24 mm |
| $\left(\begin{array}{l} \text { NEURO } \\ \text { CLASSIC } \end{array}\right.$ | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| $\left(\mathbf{N E U R O}^{\mathrm{Hos}}\right.$ | holder (1) | - | - | - | PE4000-LR | - | - |
|  | joint retainer (2) | - | - | - | PE1025-LR | - | - |
| NEURO <br> CLASSIC-SPRING | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| NEURO CLASSIC-SWNG | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| $\frac{\text { NEURO }}{\text { VAR:O-CLASSIC }}$ | holder (1) | - | - | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | - | - | PE1012-LR | PE1013-LR | PE1025-LR | - |
| $\frac{\text { NEURO }}{\text { VAR.O-CLASSIC' }}$ | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| NEURO VAR!O | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| NEURO VARIO2 | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| $\frac{\text { NEURO }}{\text { VAR!O-SPRING }}$ | holder (1) | - | - | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | - | - | PE1012-LR | PE1013-LR | PE1025-LR | - |
| $\frac{\text { NEURO }}{\text { VARIO-SPRING } 2}$ | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| $\frac{\text { NEURO }}{\text { VARIO-SWNG }}$ | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| NEURO SWING-CLASSIC | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| $\begin{gathered} \text { NEURO } \\ S_{S}^{\text {WING }} \\ \hline \phi \end{gathered}$ | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | PE4000-LR |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | PE1127-LR |
| $\begin{aligned} & \text { NEURO } \\ & \text { SNING }_{2} \end{aligned}$ | holder (1) | PE1001-LR | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1025-LR | - |
| $\underset{N_{-\infty}^{\text {SW/Na }}}{\text { NEU }}$ | holder (1) | - | - | - | - | PE4000-LR | - |
|  | joint retainer (2) | - | - | - | - | PE1025-LR | - |
|  | holder (1) | - | PE1001-LR | PE4000-LR | PE4000-LR | PE4000-LR | - |
|  | joint retainer (2) | - | PE1011-01/LR | PE1012-LR | PE1025-LR | PE1025-LR | - |

Holders and Joint Retainers

| Holders and Joint Retainers |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| System Knee Joints and Articulated System Side Bars | Tools | Article Numbers for System Width |  |  |  |  |
|  |  | 10 mm | 12 mm | 14 mm | 16 mm | 20 mm |
| NEUROCLASSIC | holder (1) | - | PE2000-LR | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | PE1012-LR | PE1013-LR | PE1025-LR | PE1025-LR |
| NEURO <br> VARIO <br> zero | holder (1) | - | PE2000-LR | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | PE1012-LR | PE1013-LR | PE1025-LR | PE1025-LR |
| NEURO CLASSIC | holder (1) | - | PE2000-LR | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | PE1012-LR | PE1013-LR | PE1025-LR | PE1025-LR |
| NEURO VARIO | holder (1) | - | PE2000-LR | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | PE1012-LR | PE1013-LR | PE1025-LR | PE1025-LR |
| $\begin{aligned} & \text { NEURO } \\ & \text { VAR!O2 } \end{aligned}$ | holder (1) | - | PE2000-LR | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | PE1012-LR | PE1013-LR | PE1025-LR | PE1025-LR |
| $\frac{\text { NEURO }}{\text { VAR:O-SWNG }}$ | holder (1) | - | PE2000-LR | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | PE1012-LR | PE1013-LR | PE1025-LR | PE1025-LR |
| Cneuro ACTIVE | holder (1) | PE2000-LR | - | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (2) | PZ4100-LR | - | PZ4100-LR | PZ3100-LR | PZ3100-LR |
| NEURO CLASSIC | holder (1) | - | - | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | - | PE1012-LR | PE1122-LR | PE1123-LR |
| NEURO MATIC | holder (1) | - | - | - | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | - | - | PE1015-LR | PE1025-LR |
| NEURO TRONIC | holder (1) | - | - | - | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | - | - | PE1015-LR | PE1025-LR |
| NEURO HiTRONIC | holder (1) | - | - | - | - | PE2000-LR |
|  | joint retainer (3) | - | - | - | - | PE1025-LR |
| $\frac{\text { NEURO }}{\text { LOCK }}$ | holder (1) | - | - | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | - | PE1012-LR | PE1013-LR | PE1015-LR |
| $\frac{\text { NEURO }}{\text { LOCK }}$ | holder (1) | - | PE2000-LR | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | PE1121-LR | PE1122-LR | PE1123-LR | PE1125-LR |
| NEURO <br> Lock Function | holder (1) | - | PE2000-LR | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | PE1121-LR | PE1122-LR | PE1123-LR | PE1125-LR |
|  | holder (1) | - | PE2000-LR | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | PE1121-LR | PE1122-LR | PE1123-LR | PE1125-LR |
| $\underbrace{\text { NEURO }}_{\text {LOCK }_{j}^{400}}$ | holder (1) | - | - | PE2000-LR | PE2000-LR | PE2000-LR |
|  | joint retainer (3) | - | - | PE1012-LR | PE1122-LR | PE1123-LR |

Spare Parts Tools


| Holder (Fig. 1) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Tool | Fig. | Description | Article Number | Quantity |
| PE1001-LR | 1a | round material, aluminium | RM0050-AL060 | 1 |
|  | 1 b | slotted pan head screw | SC2104-L04 | 1 |
|  | 1 c | square: $11 \times 11 \times 20 \mathrm{~mm}$ | PE0102-02 | 1 |
|  | 1d | polyamide bushing | BP0908-L05 | 1 |
|  | 1 e | headless pin with hexagon socket | SC9604-L04 | 1 |
| PE2000-LR | 1a | round material, aluminium | RM0120-AL100 | 1 |
|  | 1 b | cheese head screw with hexagon socket | SC4005-L08 | 1 |
|  | 1 c | square: $15 \times 15 \times 40 \mathrm{~mm}$ | PE0102-01 | 1 |
|  | 1d | polyamide bushing | BP1210-L10 | 1 |
|  | 1 e | headless pin with hexagon socket | SC9606-L04ST | 1 |
| PE4000-LR | 1a | round material, aluminium | RM0080-AL100 | 1 |
|  | 1 b | cheese head screw with hexagon socket | SC4005-L08 | 1 |
|  | 1 c | square: $15 \times 15 \times 30 \mathrm{~mm}$ | PE0102-00 | 1 |
|  | 1d | polyamide bushing | BP1210-L10 | 1 |
|  | 1 e | headless pin with hexagon socket | SC9606-L04ST | 1 |


| Spare Parts Round Material |  |  |  |
| :---: | :---: | :---: | :---: |
| Article Number | Fig. |  | Description |
| RMO300-AL100 | w/o fig. | round material, aluminium, 300 mm long | Unit |


| Monocentric System Joints (Fig. 2) |  |  |  |  | ners for |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | NEURO ACTIVE System Joints/Articulated System Side Bars (Fig. 3) |  |
| PE1010-01/LR | PE1011-01/LR | PE1012-LR | PE1013-LR | PE1015-LR | PZ3100-LR | PZ4100-LR |
| PE1025-LR | PE1121-LR | PE1122-LR | PE1123-LR | PE1125-LR |  |  |
| PE1127-LR |  |  |  |  |  |  |
|  |  |  |  |  |  |  |


| Joint Retainers for Monocentric System Joints (Fig. 2) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Tool | Fig. | Scope of Delivery | Article Number | Quantity |
| PE1010-01/LR | 2a | joint retainer | PE0102-07 | 1 |
|  | 2 b | retaining screw | SC4034-L14/1 | 1 |
| PE1011-01/LR | 2a | joint retainer | PE0102-08 | 1 |
|  | 2 b | retaining screw | SC4034-L18/1 | 1 |
| PE1012-LR | 2a | joint retainer | PE0102-10 | 1 |
|  | 2 b | retaining screw | SC4035-L13 | 1 |
| PE1013-LR | 2a | joint retainer | PE0102-11 | 1 |
|  | 2 b | retaining screw | SC4035-L14 | 1 |
| PE1015-LR | 2a | joint retainer | PE0102-11 | 1 |
|  | 2 b | retaining screw | SC4035-L15 | 1 |
| PE1025-LR | 2a | joint retainer | PE0102-11 | 1 |
|  | 2 b | retaining screw | SC4035-L15/1 | 1 |
| PE1121-LR | 2a | joint retainer | PE0102-09 | 1 |
|  | 2 b | retaining screw | SC4034-L18/1 | 1 |
| PE1122-LR | 2a | joint retainer | PE0102-10 | 1 |
|  | 2 b | retaining screw | SC4035-L17 | 1 |
| PE1123-LR | 2a | joint retainer | PE0102-11 | 1 |
|  | 2 b | retaining screw | SC4035-L20 | 1 |
| PE1125-LR | 2a | joint retainer | PE0102-11 | 1 |
|  | 2 b | retaining screw | SC4035-L22/1 | 1 |
| PE1127-LR | 2a | joint retainer | PE0102-12 | 1 |
|  | 2 b | retaining screw | SC4035-L18 | 1 |

Joint Retainers for NEURO ACTIVE System Joints/Articulated System Side Bars (Fig. 3)

| Tool | Fig. | Scope of Delivery | Article Number | Quantity |
| :---: | :---: | :---: | :---: | :---: |
| PZ3100-LR | 3 a | joint retainer | PZ0310 | 1 |
|  | 3 b | $5^{\circ}$ flexion stop | BK9051-F005 | 1 |
|  | 3 c | slotted pan head screw | SC2103-L08 | 2 |
|  | 3d | retaining screw | SC4048-L16 | 2 |
| PZ4100-LR | 3 a | joint retainer | PZ0410 | 1 |
|  | w/o fig. | $0^{\circ}$ flexion stop | KS9402-F000 | 1 |
|  | 3 b | $5^{\circ}$ flexion stop | KS9402-F005 | 1 |
|  | 3 c | slotted pan head screw | SC2103-L05 | 2 |
|  | 3d | retaining screw | SC4038-L16 | 2 |

## Tools



Fig. 1


Fig. 2


Fig. 3


Fig. 4


Fig. 5

## Bolts for Trial with Knurled Nut (Fig. 1)

| Article Number | Description | Unit |
| :---: | :---: | :---: |
| PS2000-010 | $10 \times$ bolts for trial with knurled nut (bolt M3 $\times 20$ ) | package |

Application: used to screw together the bands and system side bars for producing a trial fitting orthosis

| Reamer (Fig. 2) |  |  |  |
| :---: | :---: | :---: | :---: |
| Article Number |  | Description | Unit |
| WZ1225-070 | reamer $7.0 \mathrm{~mm}, \mathrm{H7}$ |  | piece |
| WZ1225-080 | reamer 8.0 mm , H 7 |  | piece |
| WZ1225-096 | reamer $9.6 \mathrm{~mm}, \mathrm{H} 7$ |  | piece |
| WZ1225-105 | reamer $10.5 \mathrm{~mm}, \mathrm{H} 7$ |  | piece |
| WZ1225-115 | reamer $11.5 \mathrm{~mm}, \mathrm{H} 7$ |  | piece |
| WZ1225-130 | reamer 13mm, H 7 |  | piece |
| WZ1225-150 | reamer $15 \mathrm{~mm}, \mathrm{H} 7$ |  | piece |

Application: for reaming the bearing nut bore before inserting a repair bushing

| Assembly Aid for Cover Plate (Fig. 3) |  |  |
| :---: | :---: | :---: |
| Article Number | Description | Unit |
| WE9303-SF | assembly aid for cover plate for NEURO VARIO-SPRING system ankle joints, 16 and 20 mm system width | piece |

Application: for an easier tensioning of the functional unit's pressure spring when assembling the NEURO VARIO-SPRING system ankle joint

| Sliding Washer Centring Pin (Fig. 4) |  |  |  |  |  |  |  |  | Unit |
| :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Article Number | sliding washer centring pin for NEURO SWING Carbon system ankle joint, NEURO CLASSIC Carbon system ankle joint, | piece |  |  |  |  |  |  |  |
| WE5500 | NEURO LOCK Carbon and NEURO CLASSIC Carbon system knee joints |  |  |  |  |  |  |  |  |

Application: for positioning the sliding washers when assembling the NEURO SWING Carbon system ankle joint, NEURO CLASSIC Carbon system ankle joint, the NEURO LOCK Carbon and NEURO CLASSIC Carbon system knee joints

| Assembly/Lamination Dummy for System Stirrup (Fig. 5) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Article Number for System Width |  |  |  |  |
| 14 mm | 16 mm | 20 mm | Description | Unit |
| SF0912-1 | SF0913-1 | SF0915-1 | assembly/lamination dummy for system stirrup | piece |

Application: for positioning the system stirrup when making a new foot piece or when replacing the system stirrup. Due to the assembly/lamination dummy replacing the joint's upper part, there is no need to produce a new orthosis.

| Parallel Alignment Gauge |  | Description |
| :---: | :--- | :--- |
| Fig. | Article Number |  |
| 6 | PS1000 | parallel alignment gauge |
| $6 a$ | PS0102 | centering screw |
| 6b | PS0101 | guide bushing |
| 6c | PS0100-L060 | aligning pin, length: 60 mm |
| 6d | PS0100-L090 | aligning pin, length: 90 mm |
| 6e | PS0100-L120 | aligning pin, length: 120 mm |



Application: for checking the parallel alignment of system knee and system ankle joints as well as system stirrups on orthoses


Fig. 7


Fig. 9
Fig. 10
Fig. 11
Fig. 12
Fig. 13
Fig. 14
Fig. 15
Fig. 16
Fig. 17
Drilling Jig (Fig. 7)
Article Number
drilling jig for all system widths

Description
BS1000
drilling jig for all system widths
piece
Application: for precisely drilling holes in the system side bars of all system widths (for system side bars see catalogue page J1)

| Easy Cutter (Fig. 8) |  | Description |  |
| :---: | :---: | :---: | :---: | :---: |
| Article Number |  | Unit |  |
| WZ8083-01 | electric scissors to cut aramid and carbon fibres |  | piece |


| Spare Parts Easy Cutter |  |  |  |
| :--- | :--- | :--- | :--- |
| Article Number |  | Description | Unit |
| WZ8083-01/1 | cutting head for electrical scissors Easy Cutter |  | piece |

Application: for precisely cutting curves and straight cuts into technical and synthetic as well as natural materials (for materials see catalogue page L1ff.)

| Hexalobular Screwdriver (Fig. 9-15) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Fig. | Article Number |  | Description | Unit |
| 9 | WZ5114-T06 | hexalobular screwdriver, T-handle, T6 |  | piece |
| 10 | WZ5114-T08 | hexalobular screwdriver, T-handle, T8 |  | piece |
| 11 | WZ5114-T10 | hexalobular screwdriver, T-handle, T10 |  | piece |
| 12 | WZ5114-T15 | hexalobular screwdriver, T-handle, T15 |  | piece |
| 13 | WZ5114-T20 | hexalobular screwdriver, T-handle, T20 |  | piece |
| 14 | WZ5114-T25 | hexalobular screwdriver, T-handle, T25 |  | piece |
| 15 | WZ5114-T30 | Innensechsrundschlüssel, T-Griff, T30 |  | piece |

Application: for screwing and unscrewing hexalobular socket screws

| Alignment Hexagonal Screwdriver with Spherical Head (Fig. 16-17) |  |  |  |
| :---: | :---: | :---: | :---: |
| Fig. | Article Number | Description | Unit |
| 16 | WZ5112-3010 | hexagonal screwdriver with spherical head, $3 \times 100 \mathrm{~mm}$ | piece |
| 16 | WZ5112-4010 | hexagonal screwdriver with spherical head, $4 \times 100 \mathrm{~mm}$ | piece |
| 17 | WZ5112-5010 | hexagonal screwdriver with spherical head, $5 \times 100 \mathrm{~mm}$ | piece |

Application: for screwing and unscrewing the alignment screw

| Torque Screwdriver in a Case |  |  |
| :---: | :---: | :---: |
| Fig. | Article Number | Description |
| 18 | WZ5500 | torque screwdriver in a case with 7 bits |
| 18a | - | torque screwdriver, 1-6Nm |
| 18 b | WZ5600-I30 | bit, hexagon socket, $3 \mathrm{~mm}, 25 \mathrm{~mm}$ long, for M5 screws |
| 18c | WZ5600-I40 | bit, hexagon socket, 4mm, 25 mm long, for M6 screws |
| 18d | WZ5604-T10 | bit, hexalobular socket, TX10, 25 mm long, for M3 screws and for pressing screw* 10 mm |
| 18e | WZ5604-T15 | bit, hexalobular socket, TX15, 25 mm long, for M4 screws |
| 18f | WZ5604-T20 | bit, hexalobular socket, TX20, 25 mm long, for M5/M6 screws and for pressing screw* 12 mm |
| 18 g | WZ5604-T25 | bit, hexalobular socket, TX25, 25 mm long, only for pressing screw* $14 / 16 / 20 \mathrm{~mm}$ |
| 18h | WZ5604-T30 | bit, hexalobular socket, TX25, 25 mm long, for M6 screws |

* NEURO CLASSIC-SPRING, NEURO CLASSIC-SWING, NEURO VARIO-CLASSIC 2, NEURO VARIO 2, NEURO VARIO-SPRING 2, NEURO VARIO-SWING, NEURO SWING-CLASSIC, NEURO SWING, NEURO SWING 2 and NEURO HiSWING


Application: for tightening screws with a defined torque

## Tool Case (Fig. 1)



| Tool Case |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Fig. | Art.-No. | Description | Quantity | Catalogue Page |
| 1 | WK1000 | tool case complete, filled with tools | 1 | K13 |
| - | WK1000-0 | tool case with empty storage foam inlays, for filling by yourself | 1 | - |
| 1a | PZ4100-LR | joint retainers for 10 and 14 mm NEURO ACTIVE system joints/articulated system side bars as well as articulated side bars with gear segments*, 16 mm centre distance | 2 | K10 |
| 1 b | PZ3100-LR | joint retainers for 16 and 20 mm NEURO ACTIVE system joints/articulated system side bars | 2 | K10 |
| 1 c | PZ2100-LR | joint retainers for articulated side bars with gear segments, 22 mm centre distance | 2 | - |
| 1d | PE1010-01/LR | joint retainers for all 10 mm system ankle joints (laser marking: $1 / \mathrm{Y}$ ) | 2 |  |
| 1e | PE1011-01/LR | joint retainers for all 12 mm system ankle joints (laser marking: $2 / \mathrm{Z}$ ) | 2 |  |
| 1 f | PE1121-LR | joint retainers for 12 mm NEURO FLEX MAX and NEURO LOCK MAX (laser marking: 2/A) | 2 |  |
| 1 g | PE1012-LR | joint retainers for all 14 mm system ankle joints as well as for the system knee joints 12 mm NEURO CLASSIC zero, NEURO VARIO zero, NEURO CLASSIC, NEURO VARIO, NEURO VARIO 2 and NEURO VARIO-SWING and 14 mm NEURO CLASSIC Carbon, NEURO LOCK and NEURO LOCK Carbon (laser marking: 4/B) | 4 |  |
| 1h | PE1013-LR | joint retainers for all 16 mm system ankle joints, excluding 16 mm NEURO SWING Carbon and NEURO CLASSIC Carbon, as well as for the system knee joints 14 mm NEURO CLASSIC zero, NEURO VARIO zero, NEURO CLASSIC, NEURO VARIO, NEURO VARIO 2 and NEURO VARIO-SWING and 16 mm NEURO LOCK (laser marking: 5/C) | 4 |  |
| 1 i | PE1015-LR | joint retainers for 16 mm NEURO MATIC and NEURO TRONIC as well as 20 mm NEURO LOCK (laser marking: 6/C) | 2 | K10 |
| 1j | PE1025-LR | joint retainers for all 20 mm system ankle joints and 16 mm NEURO SWING Carbon, for the system knee joints 20 mm NEURO MATIC, NEURO TRONIC and NEURO HiTRONIC as well as 16 and 20 mm NEURO CLASSIC zero, NEURO VARIO zero, NEURO CLASSIC, NEURO VARIO, NEURO VARIO 2 and NEURO VARIO-SWING (laser marking: 7/C) | 4 |  |
| 1k | PE1125-LR | joint retainers for 20 mm NEURO FLEX MAX and NEURO LOCK MAX (laser marking: 8/C) | 2 |  |
| 11 | PE1123-LR | joint retainers for 16 mm NEURO FLEX MAX and NEURO LOCK MAX as well as 20 mm NEURO LOCK Carbon and NEURO CLASSIC Carbon (laser marking: 9/C) | 2 |  |
| 1 m | PE1122-LR | joint retainers for 14 mm NEURO FLEX MAX and NEURO LOCK MAX as well as 16 mm NEURO CLASSIC Carbon and NEURO LOCK Carbon (laser marking: 10/B) | 2 |  |
| 1 n | PE1127-LR | joint retainers for 24 mm NEURO SWING (laser marking: 11/D) | 2 |  |
| 10 | PE4000-LR | holder, model technique, square: $15 \times 15 \times 30 \mathrm{~mm}$ for all $14,16,20$ und 24 mm system ankle joints | 2 |  |
| 1p | PE2000-LR | holder, model technique, square: $15 \times 15 \times 40 \mathrm{~mm}$ for all system knee joints | 2 | K9 |
| 1 q | PE1001-LR | holder, model technique, square: $11 \times 11 \times 20 \mathrm{~mm}$ for all 10 and 12 mm system ankle joints | 2 |  |
| 1 r | PS1000 | parallel alignment gauge | 1 | K11 |
| 1s | JA1001 | alignment aid $11 \times 11 \times 300 \mathrm{~mm}$ for 10 and 12 mm system ankle joints | 1 |  |
| 1t | JA1000 | alignment aid $15 \times 15 \times 300 \mathrm{~mm}$ for all $14,16,20$ and 24 mm system ankle/system knee joints as well as for 12 mm system knee joints | 2 | K4 |
| 1 u | RM0300-AL060 | round material, aluminium, $6 \times 300 \mathrm{~mm}$ | 1 | K9 |
| 1 v | RM0300-AL100 | round material, aluminium, $10 \times 300 \mathrm{~mm}$ | 1 | K9 |
| 1w | PS2000-010 | bolts for trial with knurled nut | 10 | K11 |
| 1x | BS1000 | drilling jig | 1 | K12 |
| 1 y | WE9303-SF | assembly aid for cover plate for system ankle joints with dorsiflexion assist, 16 and 20 mm system width | 1 | K11 |

* You can find articulated side bars with gear segments in our product catalogue Articulated Side Bars for Knee Orthoses.

Application: the tools included in the tool case are i.e. used for the parallel alignment of the FIOR \& GENTZ system joints. Detailed information concerning each tool is given on the corresponding catalogue pages.

You can store already bought FIOR \& GENTZ tools in the tool case with empty foam inlays.

